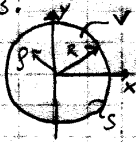


Jackson, 3.3, 3.5, 3.6, #4

3.3.



$$\sigma = C(R^2 - \rho^2)^{1/2} \Rightarrow \Phi(\vec{x} \text{ on } z \text{ axis}) = \frac{1}{4\pi\epsilon_0} \int_0^R \frac{\sigma(\rho) 2\pi\rho d\rho}{|\vec{x} - \vec{x}'|}$$

a. $r > R$

$$\begin{aligned} \Phi(z) &= \frac{1}{4\pi\epsilon_0} \int_0^R \frac{\sigma(\rho) 2\pi\rho d\rho}{\sqrt{z^2 + \rho^2}} = \frac{C}{2\epsilon_0} \int_0^R \frac{\rho d\rho}{\sqrt{z^2 + \rho^2}} \\ &= \frac{C}{2\epsilon_0} \int_0^R \frac{u du}{\sqrt{z^2 + u^2}} = \frac{C}{2\epsilon_0} \left[\sin^{-1} \frac{u}{\sqrt{z^2 + u^2}} \right]_0^R = \frac{C}{2\epsilon_0} \sin^{-1} \frac{R}{\sqrt{z^2 + R^2}} \end{aligned}$$

$$\text{on disk, } \Phi(z=0) = V = \frac{C}{2\epsilon_0} \sin^{-1}(1) = \frac{C}{2\epsilon_0} \frac{\pi}{2} \Rightarrow C = \frac{4\epsilon_0}{\pi} V$$

$$\begin{aligned} \therefore \Phi(z) &= \frac{4V}{\pi} \sin^{-1} \frac{R}{\sqrt{z^2 + R^2}} = \frac{2V}{\pi} \tan^{-1} \frac{R}{z} \quad \tan^{-1} x = \begin{cases} x - \frac{x^3}{3} + \frac{x^5}{5} - \frac{x^7}{7} + \dots & x < 1 \\ \frac{\pi}{2} - \frac{1}{x} + \frac{1}{3x^3} - \frac{1}{5x^5} + \dots & x > 1 \end{cases} \\ &= \frac{2V}{\pi} \left[\frac{R}{z} - \frac{1}{3} \left(\frac{R}{z} \right)^3 + \frac{1}{5} \left(\frac{R}{z} \right)^5 - \dots \right] = \frac{2V}{\pi} \sum_{k=0}^{\infty} \frac{(-1)^k}{2k+1} \left(\frac{R}{z} \right)^{2k+1} P_{2k}(\cos \theta) \end{aligned}$$

$$\boxed{\Phi(r, \theta, \phi) = \frac{2V}{\pi} \sum_{k=0}^{\infty} \frac{(-1)^k}{2k+1} \left(\frac{R}{r} \right)^{2k+1} P_{2k}(\cos \theta)} \quad r > R$$

$$\text{b. } \Phi(z) = \frac{4V}{\pi} \tan^{-1} \frac{R}{z} \quad \tan^{-1} x = \frac{\pi}{2} - \frac{1}{x} + \frac{1}{3x^3} - \dots \quad \frac{R}{z} > 1$$

$$= \frac{4V}{\pi} \left[\frac{\pi}{2} - \frac{1}{R/z} + \frac{1}{3} \left(\frac{z}{R} \right)^3 - \frac{1}{5} \left(\frac{z}{R} \right)^5 + \dots \right] = V - \frac{4V}{\pi} \sum_{k=0}^{\infty} \frac{(-1)^k}{2k+1} \left(\frac{z}{R} \right)^{2k+1}$$

$$\boxed{\Phi(r, \theta, \phi) = V - \frac{4V}{\pi} \sum_{k=0}^{\infty} \frac{(-1)^k}{2k+1} \left(\frac{r}{R} \right)^{2k+1} P_{2k}(\cos \theta)} \quad r < R$$

$$\text{c. } Q = \int_S \sigma ds = \frac{4\epsilon_0 V}{\pi} \int_0^R \frac{2\pi\rho d\rho}{\sqrt{R^2 - \rho^2}} = 8\epsilon_0 V \left[-\sqrt{R^2 - \rho^2} \right]_0^R = 8\epsilon_0 V R$$

$$C = \frac{Q}{V} \Rightarrow \boxed{C = 8\epsilon_0 R}$$

3.5.



$$\text{a. } G(\vec{r}, \vec{r}') = \frac{1}{|\vec{r} - \vec{r}'|} = \frac{1}{|\vec{r} - \frac{a}{r'} \frac{\vec{r}}{r}|}$$

$$= \frac{1}{(r^2 + a^2 - 2ar' \cos(\theta - \theta'))^{1/2}} = \frac{1}{(r^2 + a^2 - 2ar' \cos(\theta - \theta'))^{1/2}} \quad r > a, \theta = \theta'$$

$$\frac{\partial G}{\partial r'} \bigg|_{r'=a} = \frac{1}{(r^2 + a^2 - 2ar \cos \theta)^{3/2}} \frac{\partial}{\partial r'} (r^2 + a^2 - 2ar' \cos \theta)$$

$$\therefore \boxed{\Phi(r, \theta, \phi) = \frac{1}{4\pi} \int \frac{V(\theta', \phi')}{(r^2 + a^2 - 2ar \cos \theta)^{1/2}} d\Omega}$$

$$\text{b. the general solution: } \Phi(r, \theta, \phi) = \sum_{l=0}^{\infty} \sum_{m=-l}^l [C_{lm} r^l + D_{lm} r^{-(l+1)}] Y_{lm}(\theta, \phi)$$

$$\Phi \text{ finite at } r=0 \Rightarrow D_{lm} = 0$$

$$\Phi(a, \theta, \phi) = V(\theta, \phi) = \sum_{l=0}^{\infty} \sum_{m=-l}^l C_{lm} a^l Y_{lm}(\theta, \phi)$$

$$\int V(\theta, \phi) Y_{l'm'}^*(\theta, \phi) d\Omega = \sum_{lm} C_{lm} a^l \int Y_{lm} Y_{l'm'}^* d\Omega = C_{l'm'} a^{l'}$$

$$C_{lm} = \frac{1}{a^l} \int V(\theta, \phi) Y_{lm}^*(\theta, \phi) d\Omega$$

$$\therefore \boxed{\Phi(r, \theta, \phi) = \sum_{l=0}^{\infty} \sum_{m=-l}^l A_{lm} \left(\frac{r}{a} \right)^l Y_{lm}(\theta, \phi), \quad A_{lm} = \int d\Omega Y_{lm}^*(\theta, \phi) V(\theta, \phi)}$$

cont.

3.5 cont

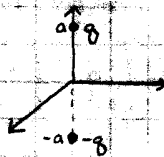
prove that these are the same -

$$\begin{aligned}\Phi(r, \theta, \phi) &= \int V(\theta', \phi') d\Omega' \sum_{l=0}^{\infty} \left(\frac{r}{a}\right)^l \frac{2l+1}{4\pi} \frac{4\pi}{2l+1} \sum_{m=-l}^l Y_{lm}^*(\theta', \phi') Y_{lm}(\theta, \phi) \\ &= \frac{1}{4\pi} \int V(\theta', \phi') d\Omega' \left[2 \sum_{l=0}^{\infty} \left(\frac{r}{a}\right)^{2l} P_l(\cos\theta) + a \sum_{l=0}^{\infty} \frac{r^l}{a^{l+1}} P_l(\cos\theta) \right] \\ &= \frac{1}{4\pi} \int V(\theta', \phi') d\Omega' \left[2ar \sum_{l=0}^{\infty} \frac{r^{l-1}}{a^{l+1}} P_l(\cos\theta) + \frac{a}{\sqrt{r^2+a^2-2ar\cos\theta}} \right] \\ &= \frac{a}{4\pi} \int V(\theta', \phi') d\Omega' \left[2r \frac{d}{dr} \frac{1}{\sqrt{r^2+a^2-2ar\cos\theta}} + \frac{1}{\sqrt{r^2+a^2-2ar\cos\theta}} \right] \\ &= \frac{a}{4\pi} \int V(\theta', \phi') d\Omega' \left[-r \frac{2r - a\cos\theta}{(r^2+a^2-2ar\cos\theta)^{3/2}} + \frac{1}{\sqrt{r^2+a^2-2ar\cos\theta}} \right]\end{aligned}$$

$$\boxed{\Phi(r, \theta, \phi) = \frac{a}{4\pi} (a^2 - r^2) \int \frac{V(\theta', \phi')}{(r^2 + a^2 - 2ar\cos\theta)^{3/2}} d\Omega'} \quad \text{as in part a.}$$

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3.6



$$\begin{aligned}a. \quad \Phi(r, \theta, \phi) &= \frac{q}{4\pi\epsilon_0} \left[\frac{1}{|r-a\hat{z}|} - \frac{1}{|r+a\hat{z}|} \right] \\ &= \frac{q}{4\pi\epsilon_0} \frac{1}{r} \left[\left(1 - 2\left(\frac{a}{r}\right)\cos\theta + \left(\frac{a}{r}\right)^2 \right)^{-1/2} + \left(1 + 2\left(\frac{a}{r}\right)\cos\theta + \left(\frac{a}{r}\right)^2 \right)^{-1/2} \right] \\ &= \frac{q}{4\pi\epsilon_0} \sum_{l=0}^{\infty} \frac{1}{r} \left(\frac{a}{r}\right)^l \left[P_l(\theta) - P_l(\pi-\theta) \right] \\ &= \frac{q}{4\pi\epsilon_0} \sum_{l=0}^{\infty} \frac{1}{r} \left(\frac{a}{r}\right)^l (1 + (-1)^{l+1}) P_l(\theta)\end{aligned}$$

$$\boxed{\Phi(r, \theta, \phi) = \frac{q}{4\pi\epsilon_0} \sum_{l=0}^{\infty} \frac{1}{2l+1} \frac{1}{r} \left(\frac{a}{r}\right)^l (1 + (-1)^{l+1}) Y_l^0(\theta, \phi)}$$

where $r_1 = r$ if $r > a$ and $r_1 = a$ if $a > r$
 $r_2 = a$ if $r > a$ and $r_2 = r$ if $a > r$

b. $ga = \rho/a = \text{const}$ $a \rightarrow 0$ $r \neq 0$

$$r > a: \quad \Phi(r, \theta, \phi) = \frac{q}{4\pi\epsilon_0} \sum_{l=0}^{\infty} \frac{1}{r} \left(\frac{a}{r}\right)^l (1 - (-1)^{l+1}) P_l(\theta)$$

$$\text{as } a \rightarrow 0, \quad = \frac{q}{4\pi\epsilon_0} \frac{2a}{r^2} P_1(\theta) = \frac{\rho \cos\theta}{4\pi\epsilon_0 r^2}$$

$$\boxed{\Phi(r, \theta, \phi) = \frac{\rho \cos\theta}{4\pi\epsilon_0 r^2}, a \rightarrow 0}$$

$$c. \quad \Phi = \sum_{l=0}^{\infty} A_l r^l P_l(\theta) \Rightarrow \Phi(r, \theta, \phi) = \frac{\rho \cos\theta}{4\pi\epsilon_0 r^2} + \sum_{l=0}^{\infty} A_l r^l P_l(\theta)$$

$$\Phi(r=b) = \frac{\rho \cos\theta}{4\pi\epsilon_0 b^2} + \sum_{l=0}^{\infty} A_l b^l P_l(\theta) = 0 \Rightarrow A_l = \begin{cases} 0 & l \neq 1 \\ -\frac{\rho}{4\pi\epsilon_0 b^3} & l=1 \end{cases}$$

$$\boxed{\Phi(r, \theta, \phi) = \frac{\rho \cos\theta}{4\pi\epsilon_0} \left[\frac{1}{r^2} - \frac{r}{b^3} \right]}$$

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(4) It is instructive to solve this problem in a more general context. Let us take the expression for the curl in Cartesian coordinates q_i

$$(\nabla \times A)_i = \epsilon_{ike} \frac{\partial}{\partial q_k} A_e$$

and transform it to the general curvilinear coordinates $q'_k(q_i)$ with the metric

$$\gamma'_{ik} = \frac{\partial q_e}{\partial q'_i} \frac{\partial q_e}{\partial q'_k}$$

According to the vector transformation law,

$$\begin{aligned} (\nabla \times A)'_i &= \frac{\partial q'_i}{\partial q_j} (\nabla \times A)_j = \frac{\partial q'_i}{\partial q_j} \epsilon_{jke} \frac{\partial}{\partial q_k} A_e = \frac{\partial q'_i}{\partial q_j} \epsilon_{jke} \frac{\partial q'_s}{\partial q_k} \frac{\partial}{\partial q'_s} A_e = \\ &= \frac{\partial q'_i}{\partial q_j} \epsilon_{jke} \frac{\partial q'_s}{\partial q_k} \frac{\partial q'_t}{\partial q_e} \frac{\partial q_m}{\partial q'_t} \frac{\partial}{\partial q'_s} A_m \end{aligned}$$

where we've used $\frac{\partial q'_s}{\partial q_e} \frac{\partial q_m}{\partial q'_t} = \delta_{em}$. If we now take into account that

$$\epsilon_{jke} \frac{\partial q'_i}{\partial q_j} \frac{\partial q'_s}{\partial q_e} \frac{\partial q'_t}{\partial q_k} = \det \left(\frac{\partial q'_i}{\partial q_j} \right) \epsilon_{ist}$$

and $\det \gamma' = \left[\det \left(\frac{\partial q'_e}{\partial q'_i} \right) \right]^2$, we obtain

$$\begin{aligned} (\nabla \times A)'_i &= \frac{1}{\sqrt{\det \gamma'}} \epsilon_{ist} \frac{\partial q_m}{\partial q'_t} \frac{\partial}{\partial q'_s} \left(\frac{\partial q_m}{\partial q'_n} A'_n \right) = \frac{1}{\sqrt{\det \gamma'}} \epsilon_{ist} \frac{\partial}{\partial q'_s} \left(\frac{\partial q_m}{\partial q'_t} \frac{\partial q_m}{\partial q'_n} A'_n \right) = \\ &= \frac{1}{\sqrt{\det \gamma'}} \epsilon_{ike} \frac{\partial}{\partial q'_k} (\gamma'_{em} A'_m) \quad \left(\text{we've used the transformation law} \right) \end{aligned}$$

$\frac{\partial^2 q_m}{\partial q'_s \partial q'_t} = \frac{\partial^2 q_m}{\partial q'_t \partial q'_s}$

In other words, in arbitrary system of curvilinear coordinates,

$$(\nabla \times A)_i = \frac{1}{\sqrt{\det \gamma}} \epsilon_{ike} \frac{\partial}{\partial q_k} (\gamma_{em} A_m)$$

Substituting $A_i \equiv \vec{A} \cdot \vec{e}_i \equiv \vec{A} \cdot \hat{e}_i / h_i$ and $\gamma_{ik} = \text{diag}(h_1^2, h_2^2, h_3^2)$ yields the desired result