

CCAT Optical Design



Germán Cortés-Medellín



National Astronomy and Ionosphere Center
Cornell University



Outline

- ◆ Telescope Optical Parameters and Design
- ◆ FOV Performance Analysis
- ◆ Sub-reflector Sensitivity Analysis
- ◆ Active Surface Segmentation Analysis
- ◆ Conclusions

CCAT Optical Design Parameters



Design: Ritchey-Chrétien/Nasmyth Focus

Input Design Parameters

	Symbol	Value	Units
Aperture Diameter	D	25	[m]
Primary Focal Ratio	f_1/D	0.6	
System Focal Ratio	$f/\#$	f/8	
Back Focal Distance	B	11	[m]
Field of View	FOV	20	[arcmin]
Minimum Operating Wavelength	λ_{\min}	200	[μm]

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Ritchey-Chrétien Design Parameters



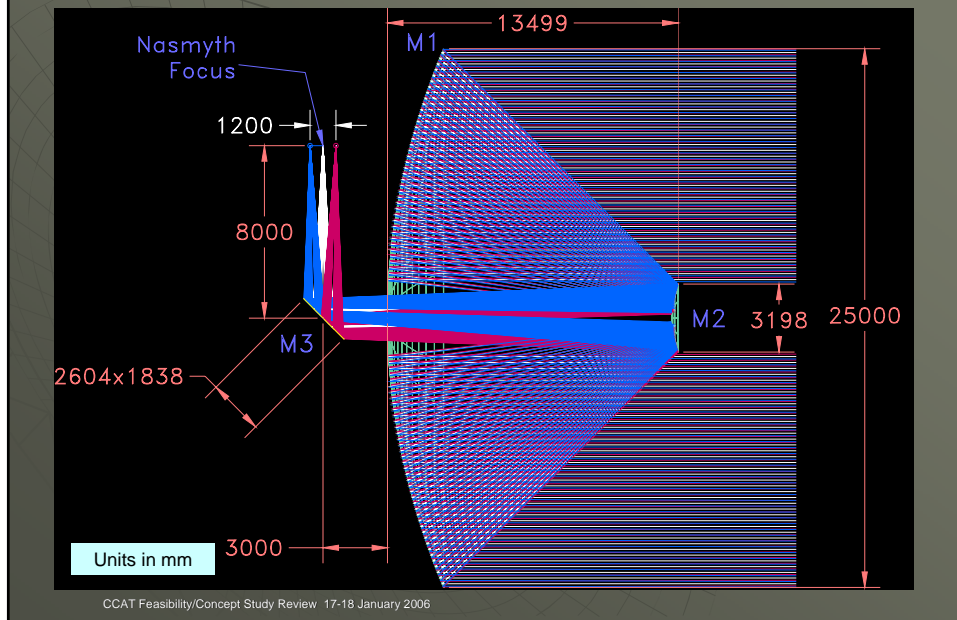
Design: Ritchey-Chrétien/Nasmyth Focus

Derived Design Parameters

	Symbol	Value	Units
M1 Diameter	D_1	25	[m]
Eccentricity	ε_1	1.000774	
Vertex Radius of Curvature	R_{C1}	30.000	[m]
Focal Distance	f_1	15.000	[m]
Edge Angle from Prime Focus	θ_1	45.24	[deg]
M2 Diameter (with provisions for FOV)	D_2	3.20	[m]
Eccentricity	ε_2	1.169098	
Vertex Radius of Curvature	R_{C2}	3.922	[m]
Edge Angle from Secondary Focus	θ_2	3.58	[deg]

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CCAT 25m Optical Layout



FOV Characteristics



- ◆ FOV Size and radius of Curvature
- ◆ Performance on-axis and at edge of FOV
- ◆ Calculated Co-Pol and Cross-Pol performance
- ◆ Performance Variation across FOV
 - Strehl
 - HPBW
 - Sidelobe level
 - Antenna Gain loss (with -11 dB Edge Taper)
 - Antenna aperture efficiency (with -11 dB Edge Taper)
- ◆ Available Number of Beams in the FOV

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CCAT Field of View Parameters



Field of View Parameters

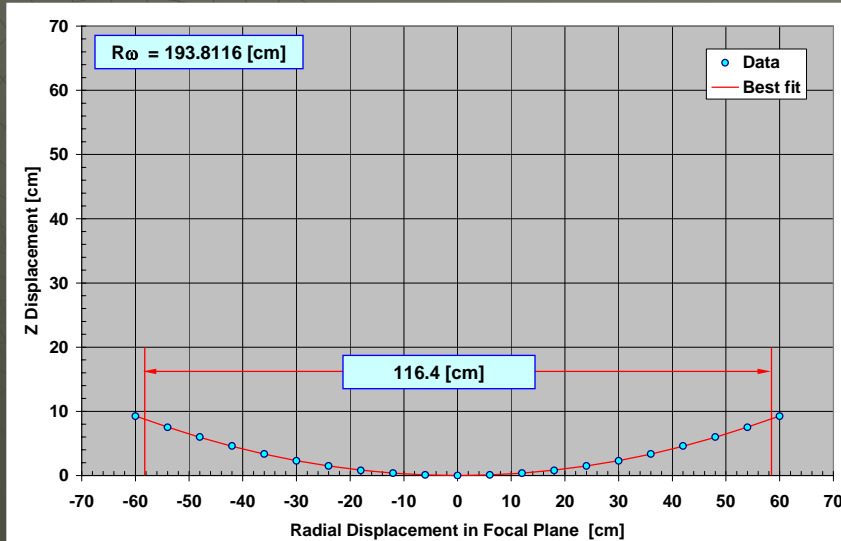
	Symbol	Value	Units
Specified Field of View	FOV	20.0	[arcmin]
Image Scale at Nasmyth Focus	IMS	1.031	[arcsec/mm]
Optimum Radius of Curvature	R_{ϕ}	1.938	[m]
Size of 20 arcmin FOV		1.164	[m]
Diffraction Spot-size at 200 μm		1.920	[mm]

Calculated Angular Aberrations

	Symbol	Value	Units
Specified Field of View	FOV	20.0	[arcmin]
Angular Tangential Coma	ATC	0.00	[arcmin]
Angular Astigmatism	AAS	2.83	[arcmin]
Angular Distortion	ADI	0.48	[arcmin]

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FOV: Optimum Focal Surface Geometry



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On Axis Performance

Wavelength: 200 [μm]
Frequency: 1499 [GHz]

Uniform Illumination Edge Taper
-11 dB

	Uniform Illumination	Edge Taper -11 dB	
HPFW Beam Width:	1.861	1.983	[arcsec]
Aperture Strehl:	100.00	100.00	[%]
Polarization Efficiency:	100.00	100.00	[%]
Beam Efficiency:	76.21	85.97	[%]
Aperture Plane Efficiency:	98.73	87.58	[%]
Spillover Efficiency	-----	88.37	[%]
Antenna Gain:	-----	110.76	[dB]
Overall Antenna Efficiency:	-----	77.40	[%]
Side Lobe Level (SLL):	-16.70	-22.27	[dB]
Cross-Polarization Level:	-326.30	-326.73	[dB]

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Performance at Edge of 20' FOV

Wavelength: 200 [μm]
Frequency: 1499 [GHz]

Uniform Illumination Edge Taper
-11 dB

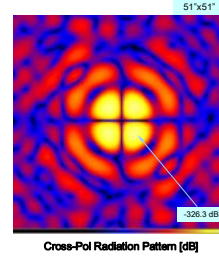
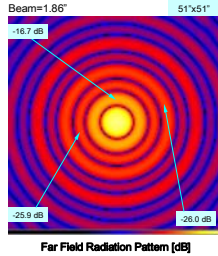
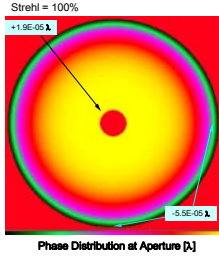
	Uniform Illumination	Edge Taper -11 dB	
HPFW Beam Width:	1.892	2.008	[arcsec]
Aperture Strehl:	96.75	98.39	[%]
Polarization Efficiency:	99.99	99.99	[%]
Beam Efficiency:	74.41	84.65	[%]
Aperture Plane Efficiency:	95.59	85.41	[%]
Spillover Efficiency	-----	88.37	[%]
Antenna Gain:	-----	110.66	[dB]
Overall Antenna Efficiency:	-----	75.48	[%]
Side Lobe Level (SLL):	-15.71	-20.89	[dB]
Cross-Polarization Level:	-51.21	-52.63	[dB]

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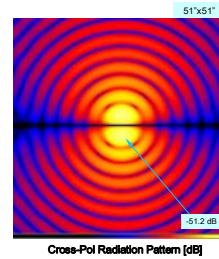
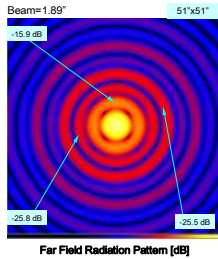
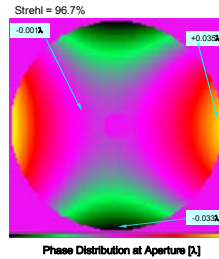
FOV Performance at 200 μm



On Axis



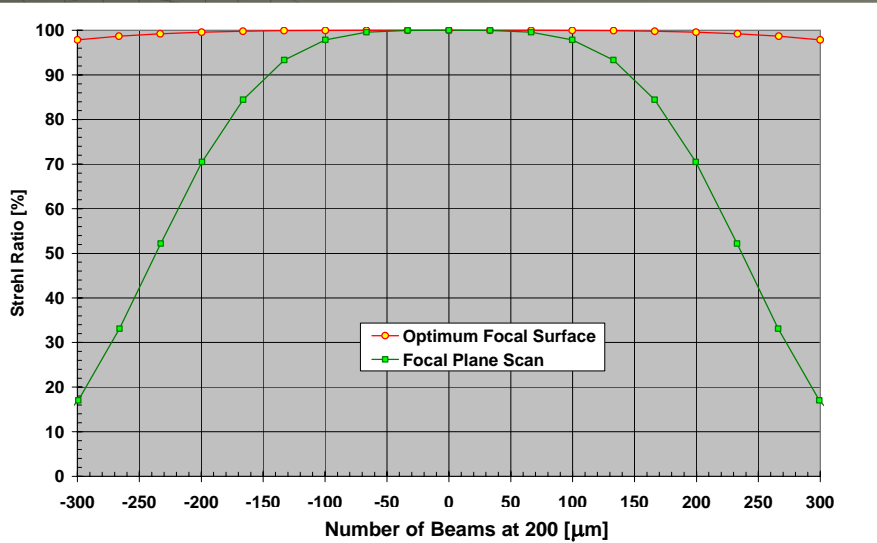
At 10' Radius



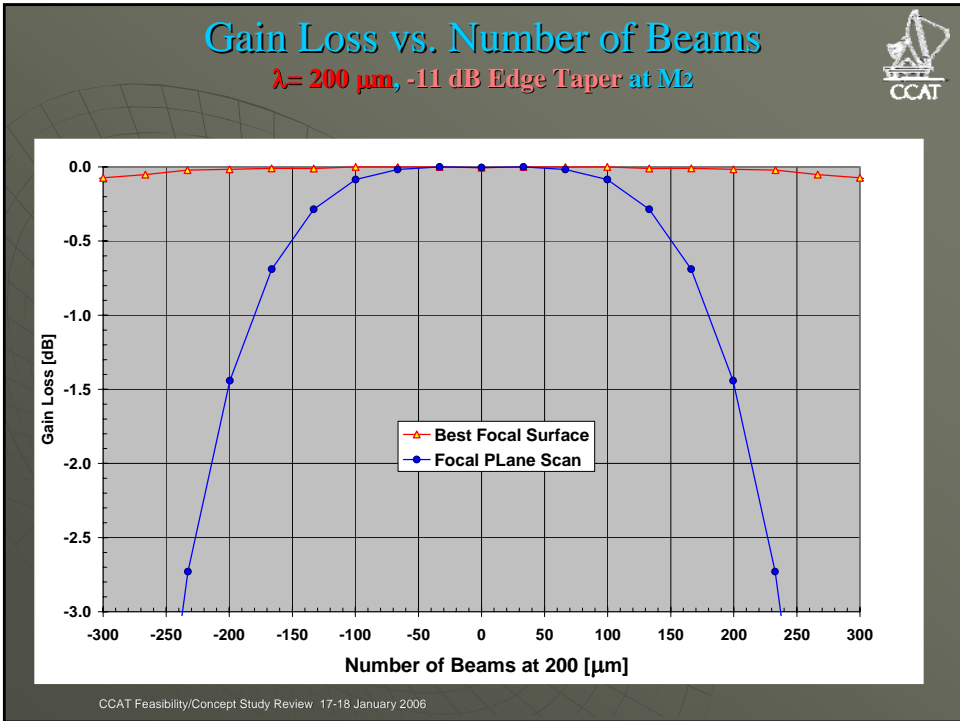
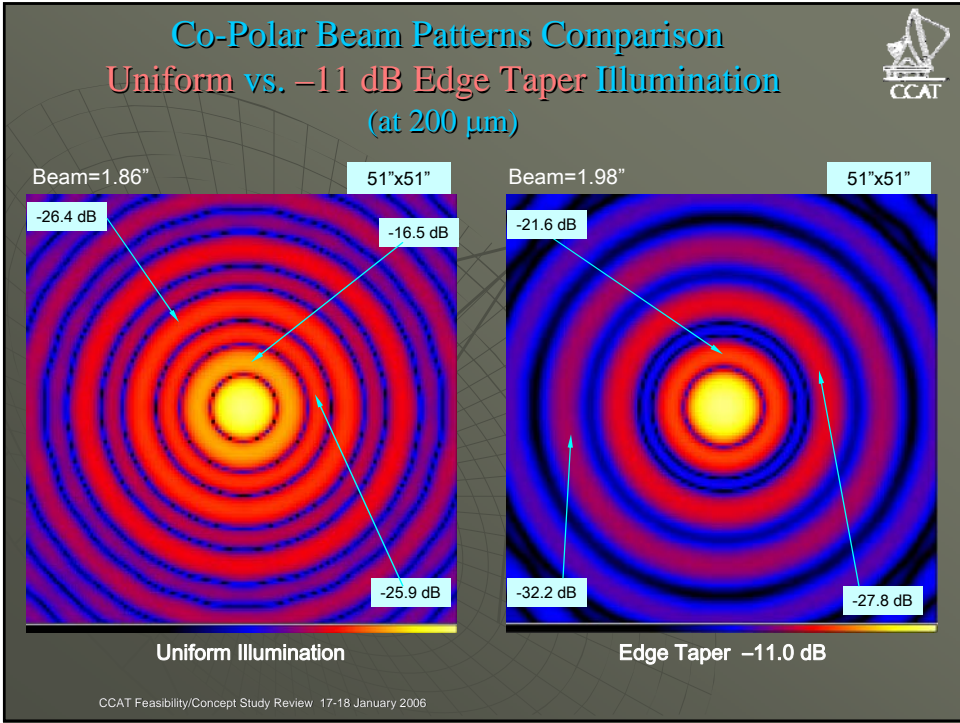
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Strehl Ratio vs. Number of Beams

$\lambda = 200 \mu\text{m}$, Uniform Illumination



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M₂ Sensitivity Analysis

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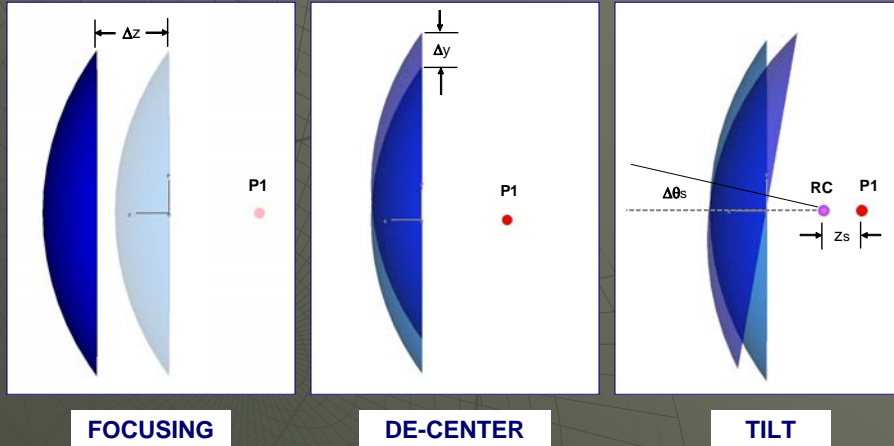


Sub-Reflector Sensitivity Analysis

- ◆ Sub-reflector Sensitivity
 - focusing
 - De-Centering
 - Tilt/Tip
- ◆ Beam Deviation due to Sub-Reflector motion
- ◆ Set limits for sub-reflector positioning based on
 - Image quality
 - Pointing requirements.
- ◆ Analyzed the image characteristics for sub-reflector chopping

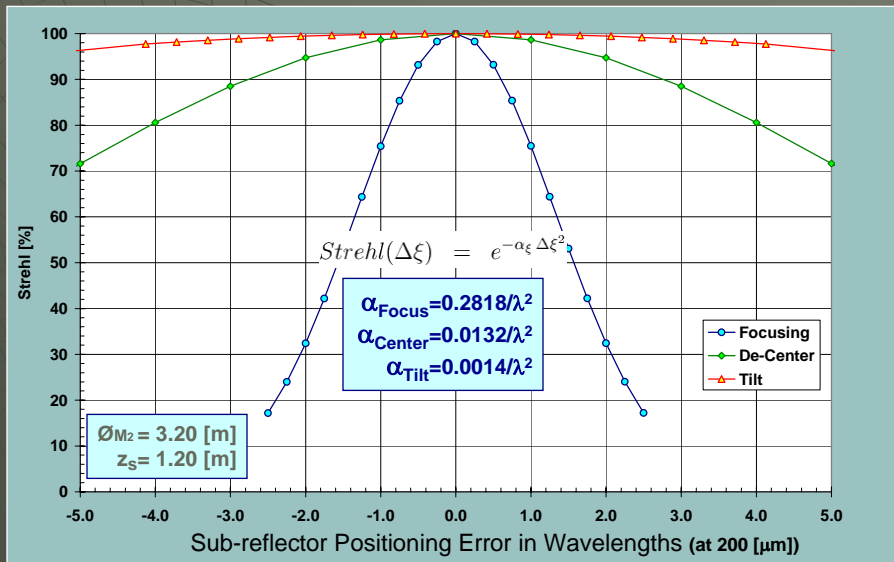
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Sub-Reflector Sensitivity Analysis



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Strehl Ratio vs. M_2 Positioning



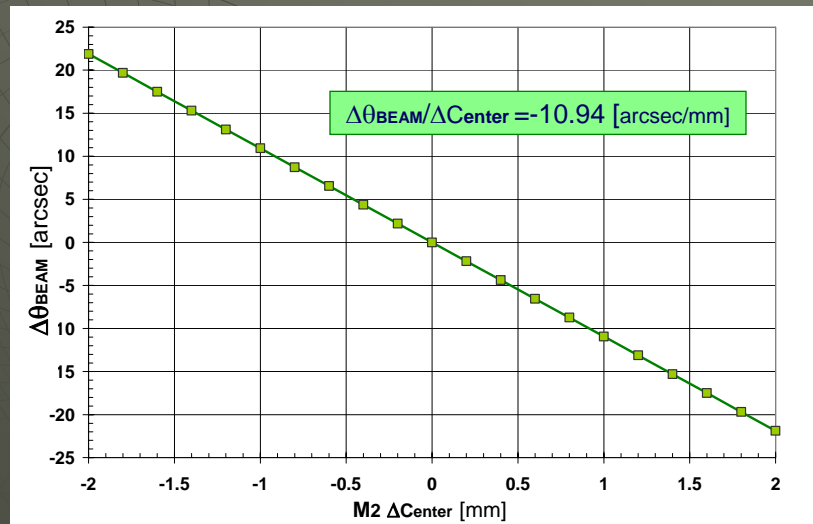
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Beam Deviation and M₂ Chopping

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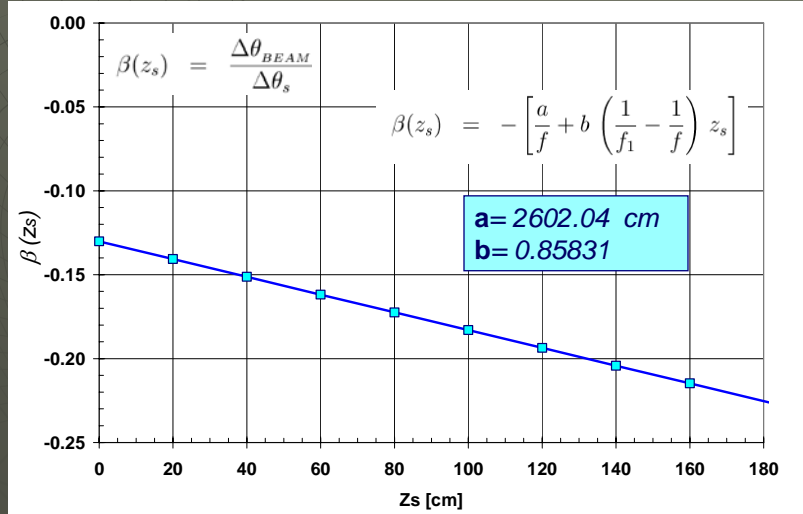
Beam Deviation vs. M₂ De-Centering



at 200 [μm]

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Beam Deviation vs. M2 Tilt



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M2 Positioning Requirements at 200 μm

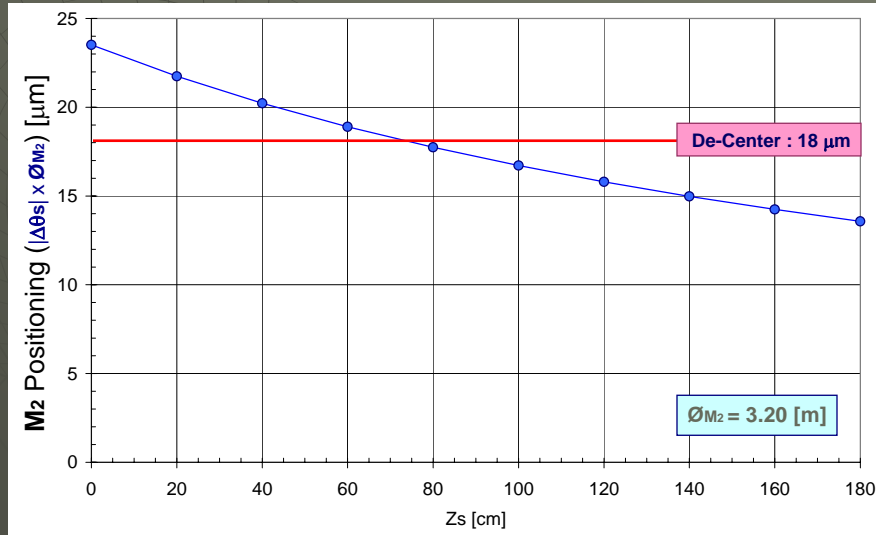


	Focus Δz [μm]	De-center Δx ² +Δy ² ^{1/2} [μm]	Tilt eqv Δθ x∅M ₂ [μm]	Tilt Δθ [arcsec]
Image Quality: Strehl > 95%	< 80.0	< 380.0	<1,085.	< 70.0
Pointing: Δθ_{BEAM} < HPBW /10	-----	< 18.1	< 16.0	< 1.03

$\emptyset_{M_2} = 3.20$ [m]
 $z_s = 1.20$ [m]

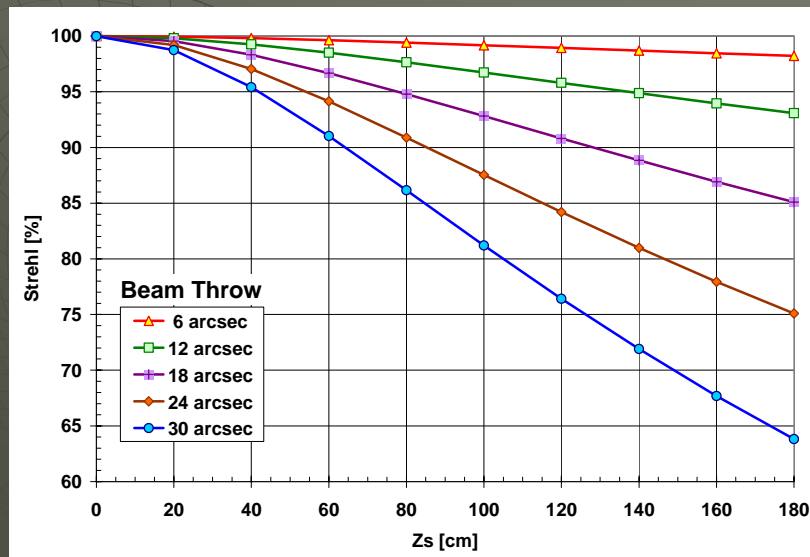
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M2 Positioning Requirements for Pointing (1/10th of the HPBW at 200 μm)



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Strehl variation vs. Beam Deviation due to Sub-Reflector Chopping



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$\lambda = 200 \mu\text{m}$



Active Surface Segmentation

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Active Surface Segmentation

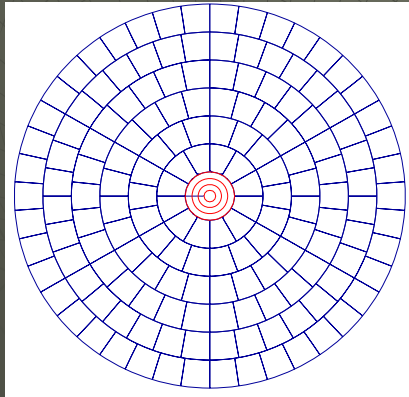
- ◆ We analyzed an active surface composed of 162 pie-shaped segments distributed with 6-fold symmetry in 6 rings
- ◆ Grating lobes symmetry, power level and location in the far field.
- ◆ Segment Positioning Error Analysis
- ◆ For Segment Piston errors, tilt/tip errors, radial and azimuth segment positioning errors, segment twists.
- ◆ Characterization of Segment positioning errors in terms of Ruze's coefficients relating segment position standard deviation errors with optical performance.
- ◆ Thermal expansion effects.

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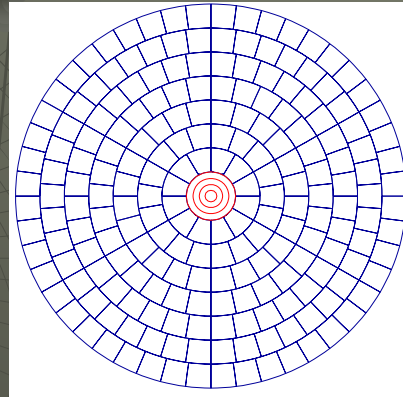
CCAT M_1 Active Surface Layout



A. 162 Segments
6 Rings



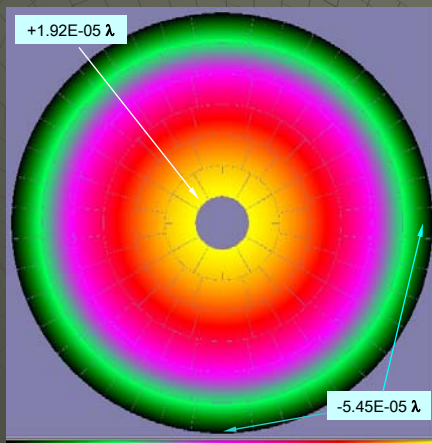
B. 210 Segments
7 Rings



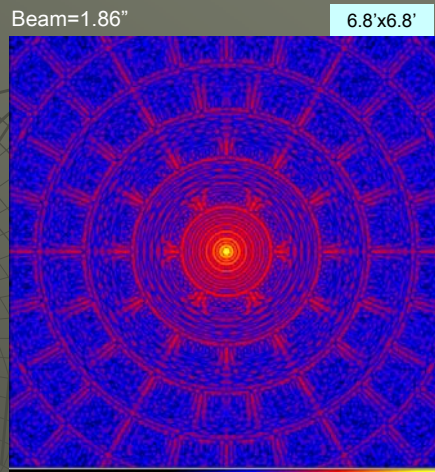
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Segmentation Effects

($\lambda=200 \mu\text{m}$, Uniform Illumination)

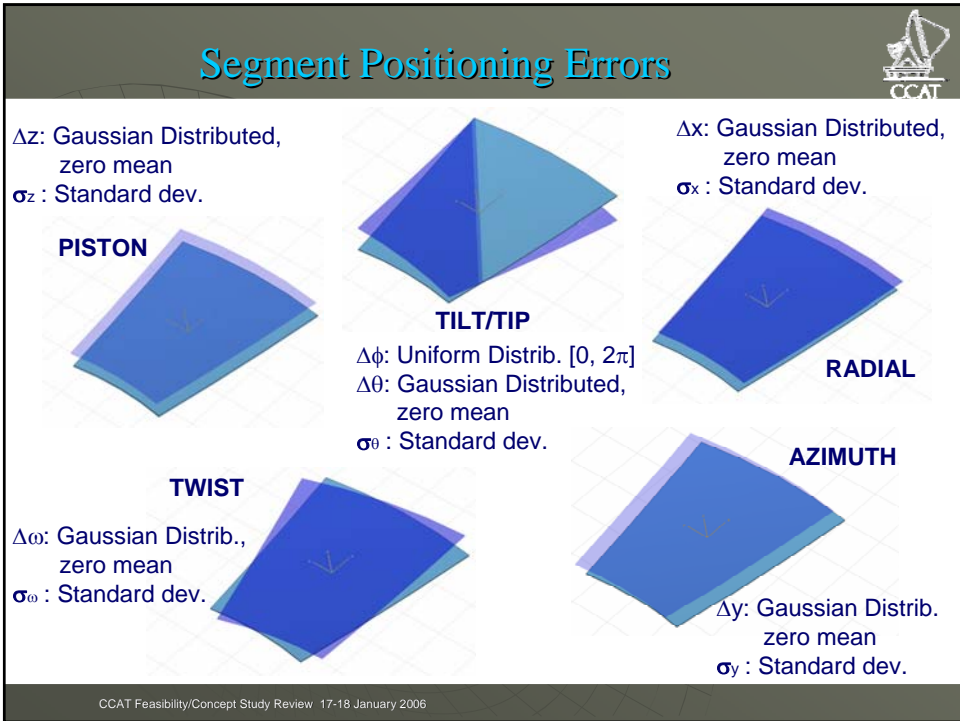
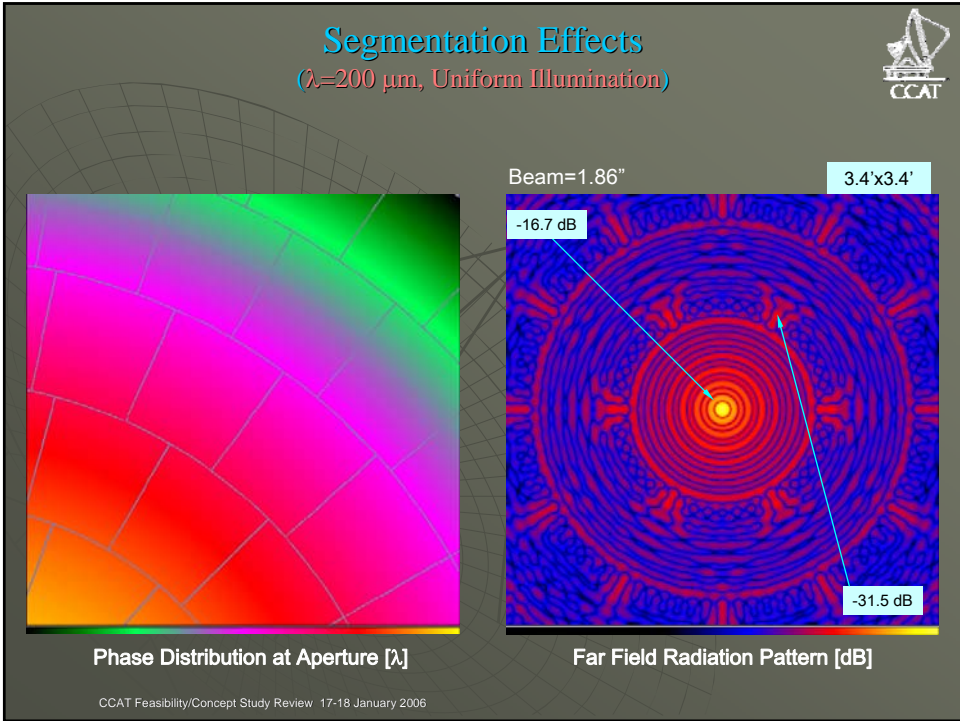


Phase Distribution at Aperture [λ]



Far Field Radiation Pattern [dB]

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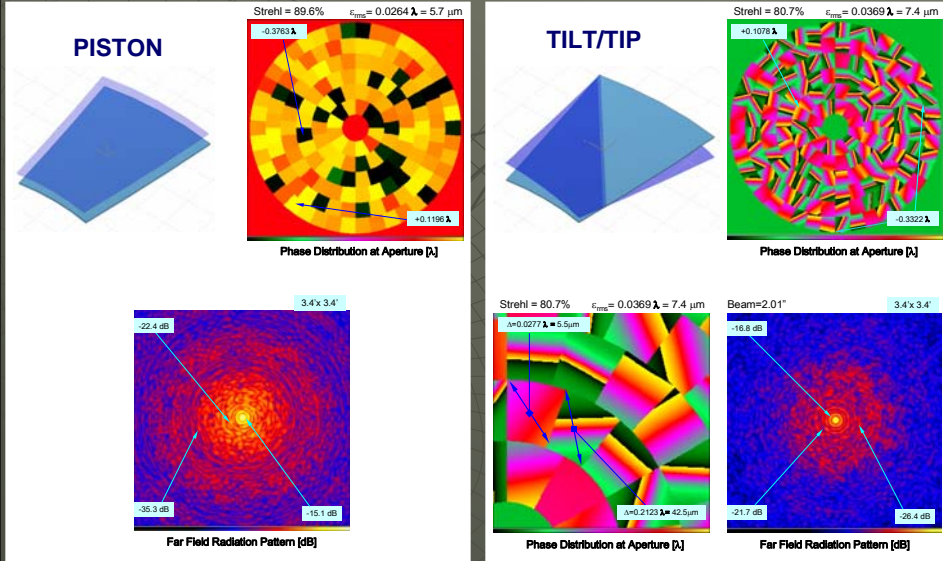


Segment Positioning Errors Samples I



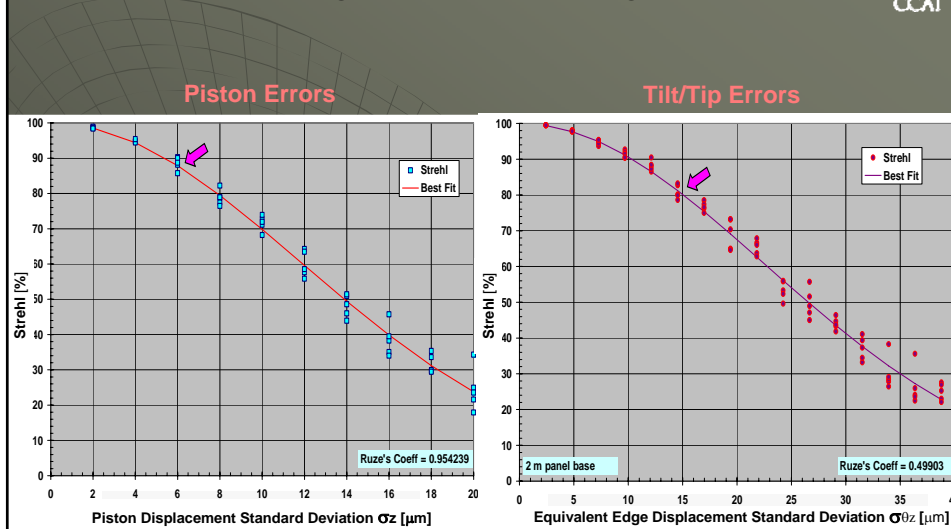
Segment Piston Errors: $\sigma_z = 6 \mu\text{m}$

Segment Tilt Errors: $\sigma_\theta = 3 \text{ arcsec}$



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Strehl vs. Segment Positioning Errors



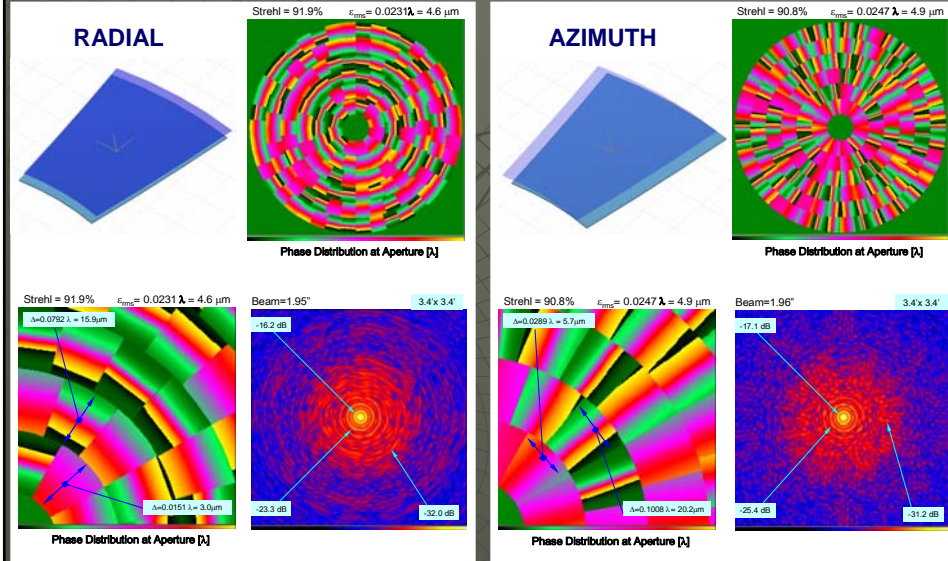
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Segment Positioning Errors Samples II



Segment Piston Errors: $\sigma_x = 0.3\text{mm}$

Segment Piston Errors: $\sigma_y = 0.3\text{mm}$



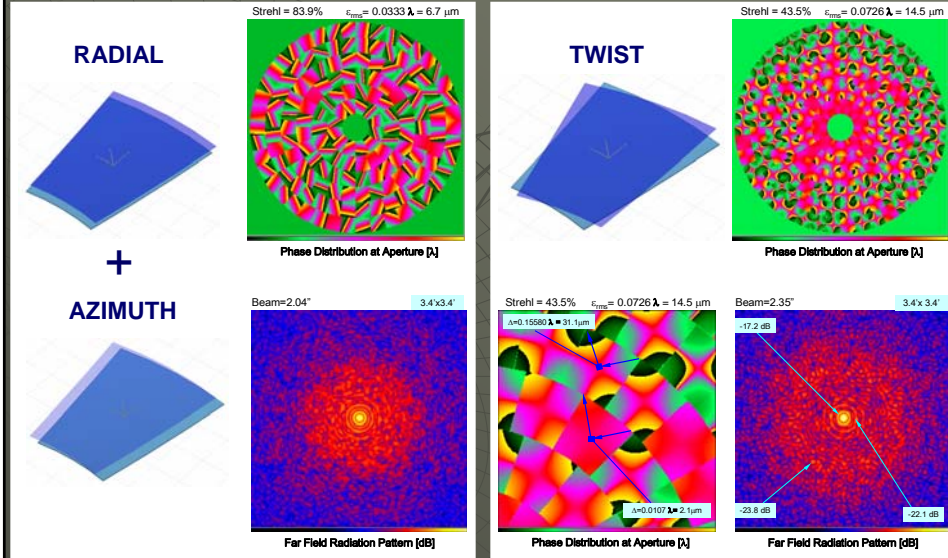
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Segment Positioning Errors Samples III



Combined Errors: $\sigma_x = \sigma_y = 0.3\text{mm}$

Segment Twist Errors: $\sigma_{\omega} = 1^\circ$

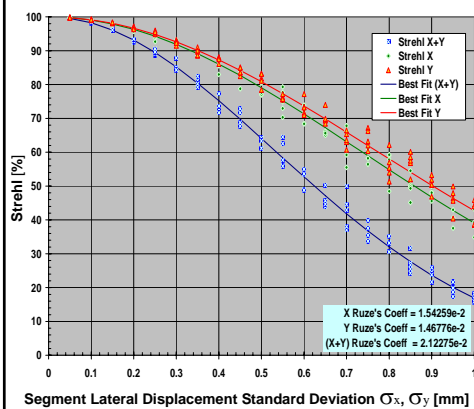


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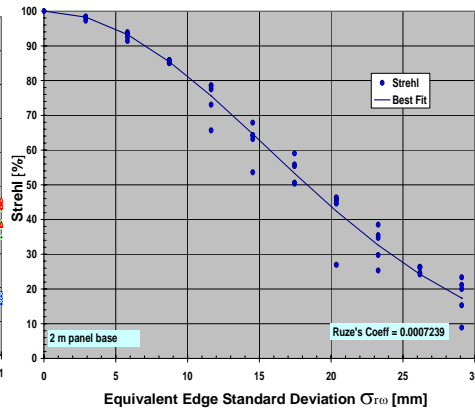
Strehl vs. Segment Positioning Errors



Combined Radial + Azimuth Errors



Segment Twist Errors



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Best Fitted Ruze's Coefficients



Ruze's Coefficient

$$\eta_{RUZE_i} = e^{-\left(\frac{4\pi \kappa_i \sigma_i}{\lambda}\right)^2}$$

- Segment Piston Displacement
- Segment Tilt/Tip (Equiv. Edge Displacement*)
- Segment Radial Displacement
- Segment Azimuth Displacement
- Segment Twist (Equiv. Edge Displacement*)

Symbol	Best Fitted Value
κ_z	0.95424
κ_{TILT}	0.49903
κ_x	0.01543
κ_y	0.01468
κ_{TWIST}	0.00073

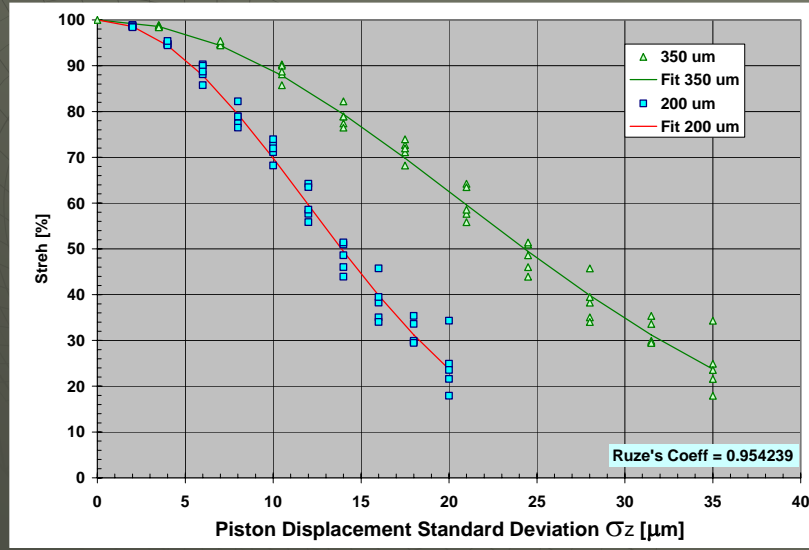
$$\epsilon_{rms} = \sqrt{(\kappa_z \sigma_z)^2 + (\kappa_{tilt} \sigma_{tilt})^2 + (\kappa_x \sigma_x)^2 + (\kappa_y \sigma_y)^2 + (\kappa_\omega \sigma_\omega)^2}$$

* Panel Base Size = 2.0 [m]

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Strehl vs. Piston Displacement

$\lambda = 200 \mu\text{m}$ and $350 \mu\text{m}$

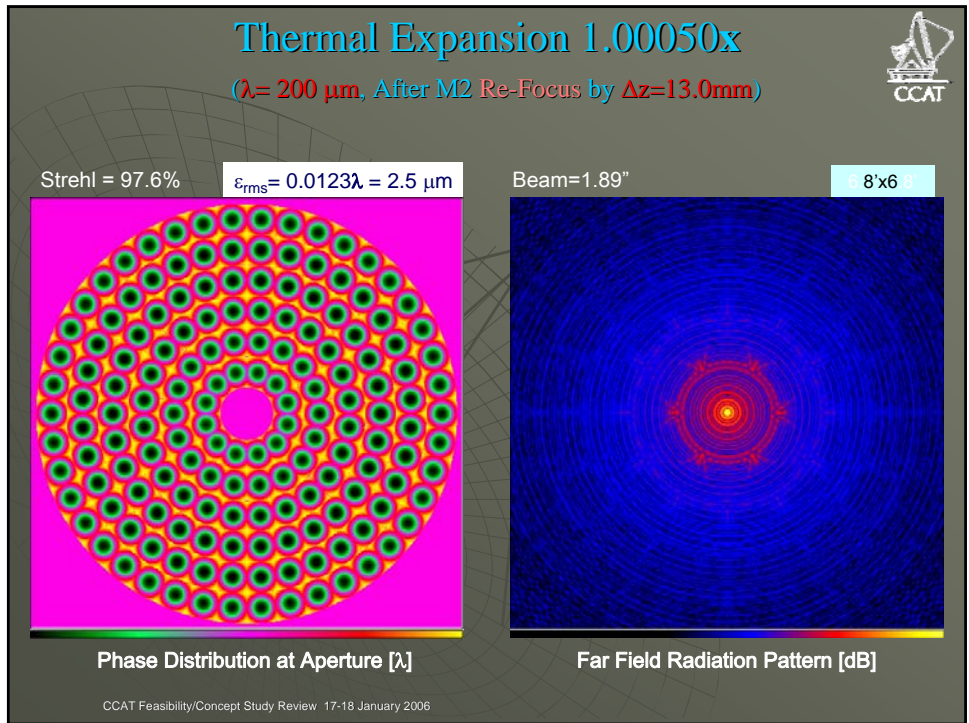
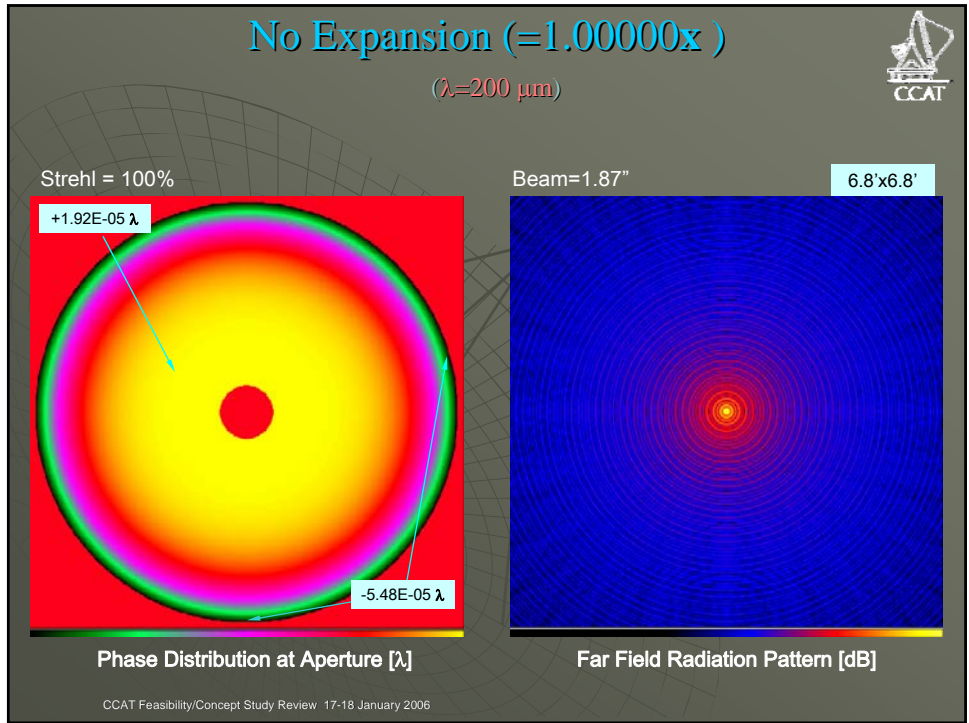


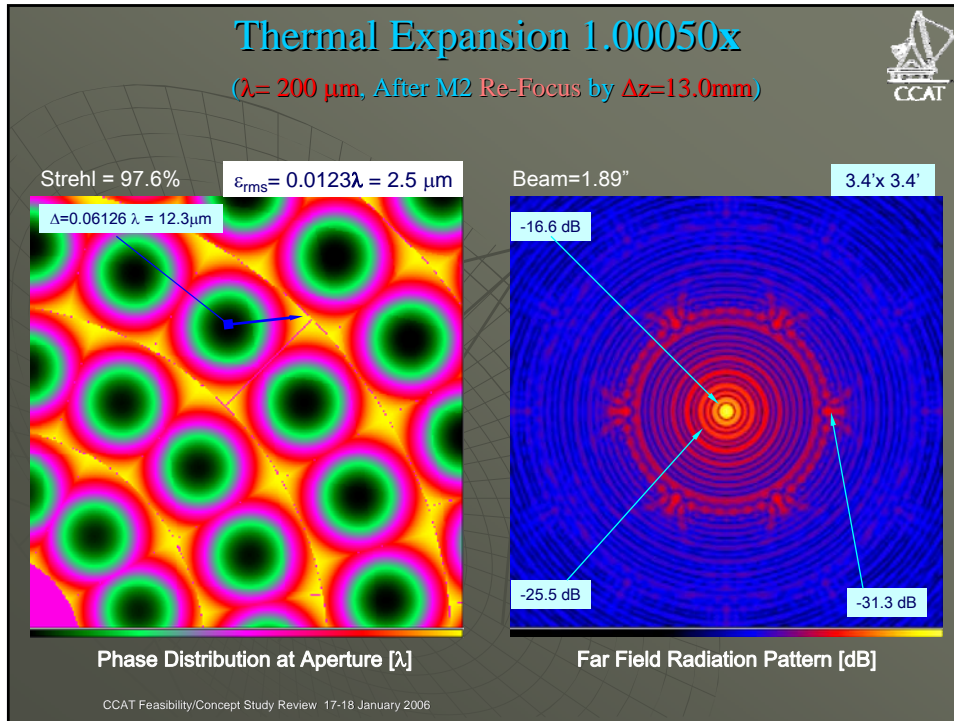
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Thermal Expansion Effects



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- ## Conclusions
- ◆ We have designed a 25m f/8 Symmetric Reflector Sub-Millimeter telescope in a double Nasmyth Ritchey-Chrétien configuration with a FOV of 20'.
 - ◆ The optimal focal surface has a diameter of 1.16 m, and a radius of curvature of 1.94 m. The calculated Strehl ratio variations over this FOV are better than 97%.
 - ◆ The 20 arcmin FOV is capable to accommodate up to 1200x1200 (Nyquist Sampled) Pixels at 200 μm .
 - ◆ The calculated maximum Cross-polar level at the edge of FOV are -51 dB and -52 dB for uniform and Gaussian illumination, respectively.
 - ◆ The Far Field Side-Lobe Level (SSL) over the FOV is > -16 dB with a uniform illumination, and better than -20 dB with a -11.0 dB Gaussian illumination taper.
 - ◆ We have obtained the sub-reflector sensitivities for focusing, de-centering and tilt/tip motion.
 - ◆ A pointing requirement of $\theta_{\text{HPFW}}/10$ at 200 μm , imposes a maximum de-centering of the sub-reflector of < 18 μm , and maximum edge-to-edge displacements of the sub-reflector, resulting from tilt/tip, between 14 μm and 24 μm , depending on the location of the center of rotation.
 - ◆ Maximum chopping amplitude is limited to 10 beam widths for 90% or better Strehl ratio at 200 μm , and maximum defocusing of < 80 μm .
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Conclusions Cont...



- ◆ We have analyzed the segmentation effect of an active surface CCAT. The gaps between segments produce a series of grating lobes levels about -31 dB down, and are distributed with a six-fold symmetry in the far field pattern.
- ◆ We have calculated the effects, in terms of Strehl ratio, of random segment positioning errors of the active surface, including piston, tilt/tip, lateral displacement and twist segment errors.
- ◆ We have found a set of coefficients relating the standard deviation of a particular segment positioning error with its resultant structural rms surface error. We have concluded that the piston errors have the largest effect on the antenna performance, followed by tip/tilt errors being half as important.
- ◆ Although, segment piston, and tilt/tip errors are directly controllable by the active surface actuators, we found that un-controllable lateral segment displacements may be compensated by tip/tilt corrections.
- ◆ Segment twist errors are not controllable, neither can be compensated by a piston-tilt actuator system alone. Nevertheless, telescope performance is very insensitive to twist errors.
- ◆ We have calculated the effects of a uniform thermal expansion of the back-structure by a factor of $1.0005x$. This produces a quadratic phase error distribution across of each of the segments, and a overall defocusing of the telescope. After refocusing the achievable Strehl ratio is better than 97%.

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A slide with a dark background and a grid pattern. The word "End" is written in the center in a light blue font. A small, faint image of a telescope or antenna is visible in the upper right quadrant of the grid.

End



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